

Electric Field Sweeping Concept for High Power Gyrotron Collectors

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Introduction to Gyrotron and Traditional Collector Beam Sweeping Systems

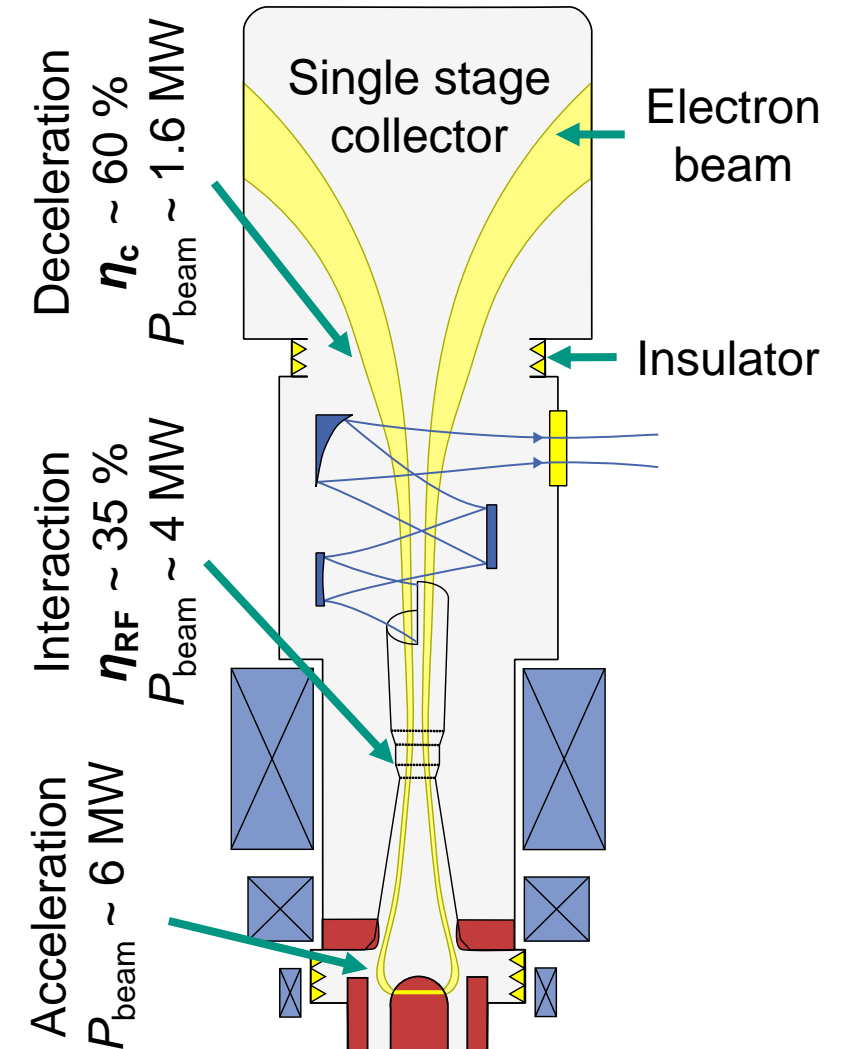
Gyrotrons for ECRH&CD in Nuclear Fusion

State of the Art

- 140 GHz, 1.5 MW continuous wave (W7-X upgrade)
- 170 GHz, 1 MW continuous wave (ITER)
- **170 GHz, 2 MW short pulse (DEMO prototype)**
- Gyrotron efficiency: $\eta_{\text{tot}} \sim 50 \%$

High thermal loading on some components

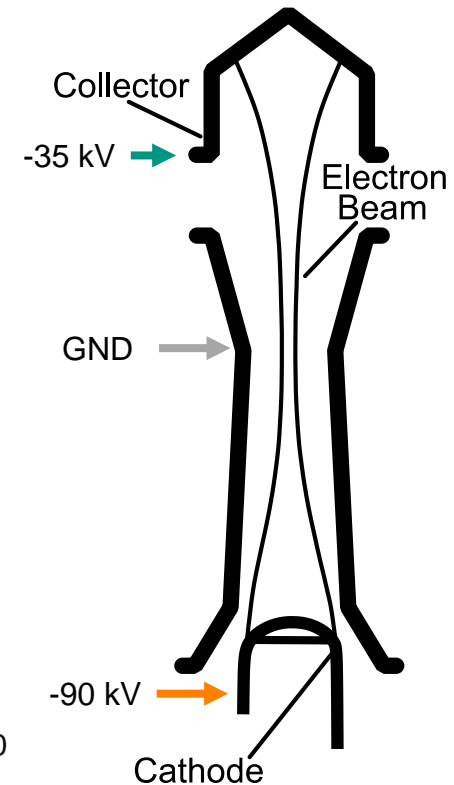
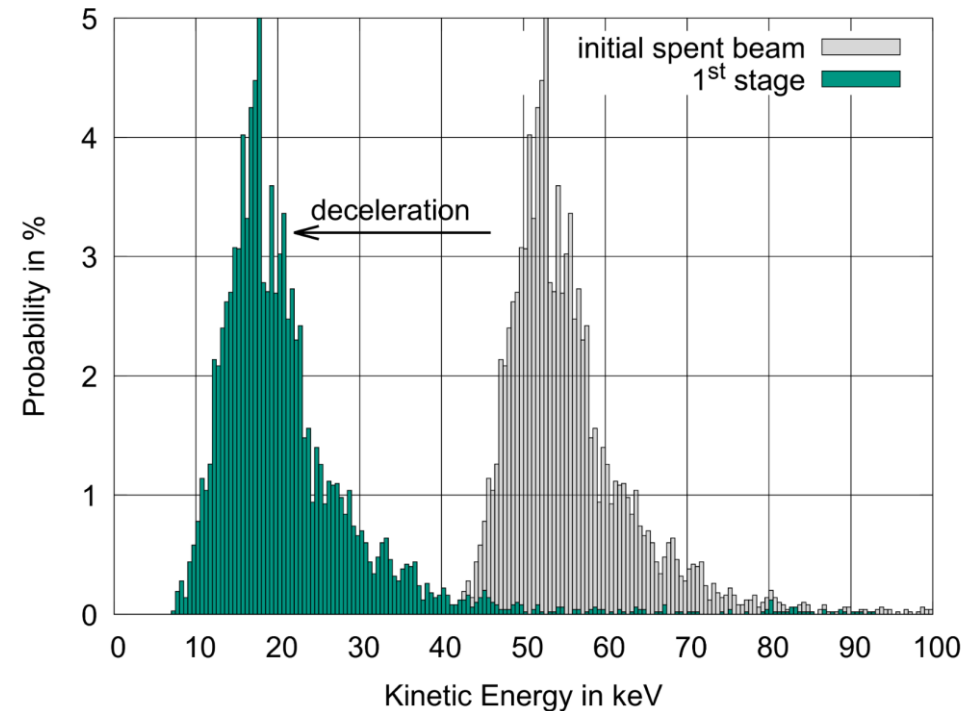
- Cavity: high power loading density \rightarrow static load
- Collector: high absolute power loading



Principle of Single-Stage Depressed Collector (SDC)

- Collector efficiency is limited to $\eta_c \sim 60\%$
 - Slowest electron
 - Widely spread energy spectrum
- Electron beam confined by strong magnetic field
 - Thin profile at collector wall
 - Very high power loading density

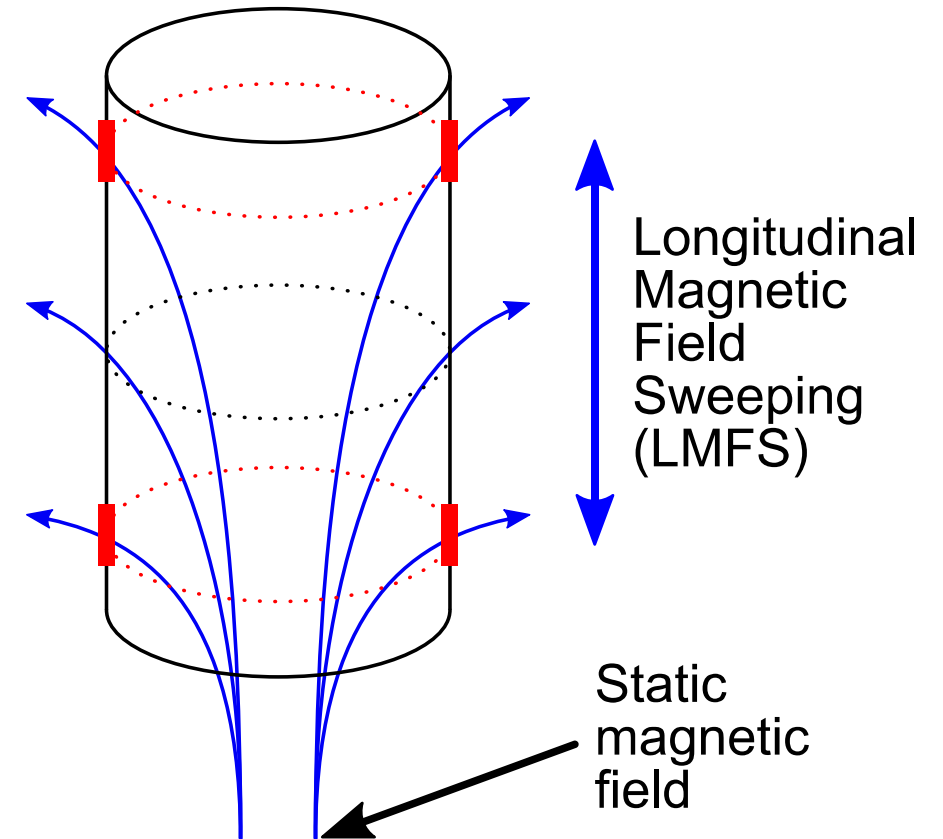
➡ Sweeping system



M. Thumm,
Fusion Engineering
and Design 2003

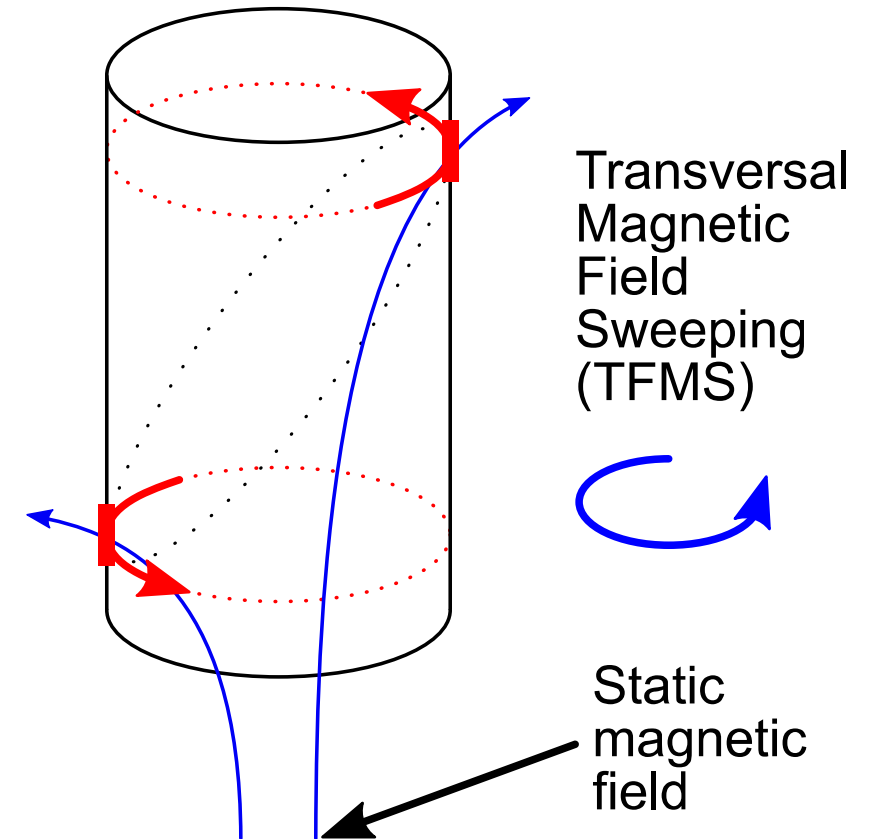
Longitudinal Magnetic Field Sweeping (LMFS)

- Electron beam swept in axial direction
 - Modification of axial magnetic field
 - Coil required around copper electrode
 - Alternating current in coil
- Sweeping frequency is limited to 7-10 Hz
 - Strong eddy currents induced in copper
 - Magnetic field inside the collector is shielded



Transversal Magnetic Field Sweeping (TMFS)

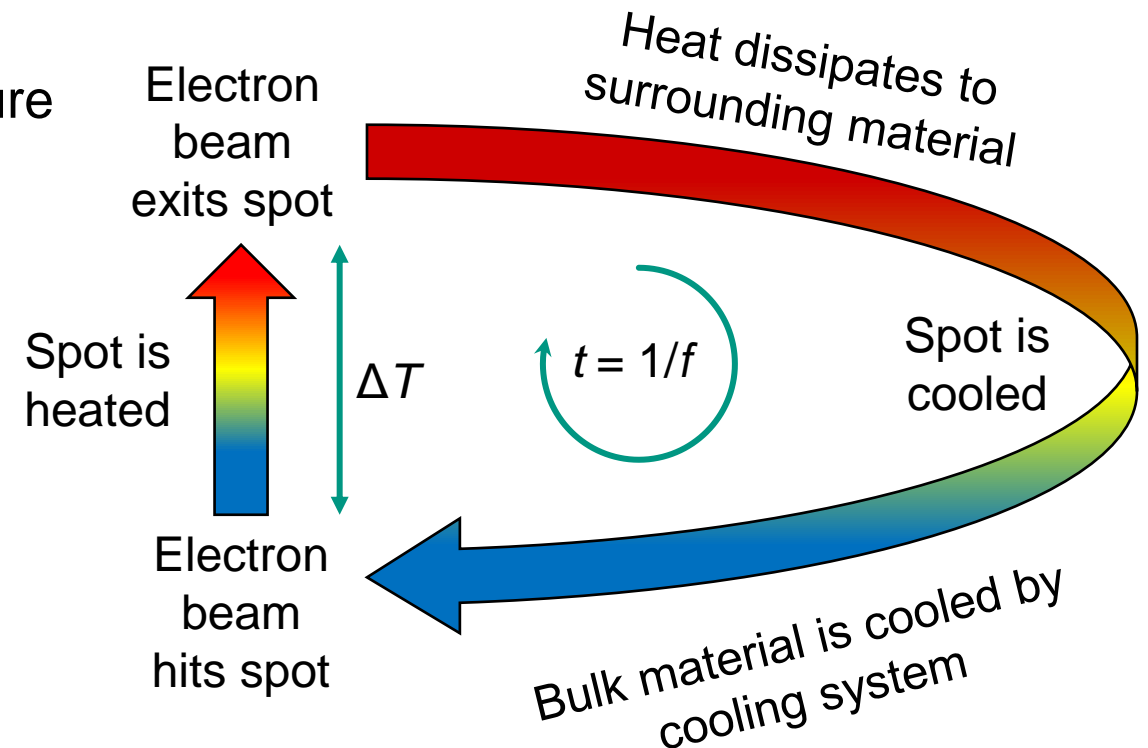
- Electron beam tilted and rotated in transversal direction
 - Modification of radial magnetic field
 - Usually six coils with 60° phase offset
 - Coils mounted below copper electrode around a stainless steel section
 - Sinusoidal current in coil
- Sweeping frequency is limited to around 50 Hz
- Can be combined with LMFS



Limitation of a Low Sweeping Frequency

- Periodic temperature variation
 - With high amplitude
 - Average temperature \ll maximal temperature
 - Less effective cooling system
- Cyclic fatigue
 - Limited lifetime of the collector
 - Cracks and plastic deformation

➡ Collector size must be increased



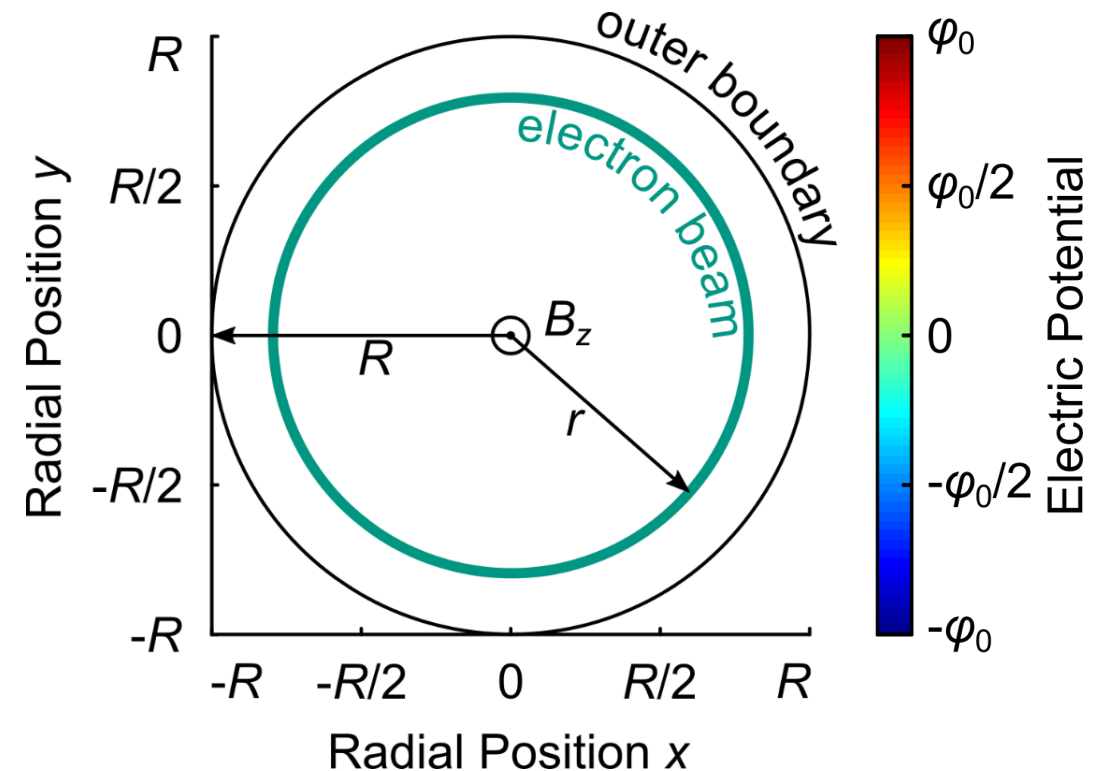
Challenges with a High Sweeping Frequency

- Electron trajectories must be modified
- Periodic variation of electric or magnetic fields
 - Magnetic field from outside → low sweeping frequency
 - Magnetic field from inside ❌
 - Electric field from outside ❌
 - Electric field from inside ✓
- Electron beam is confined by strong magnetic field
 - Electric field must create an electron drift → $E \times B$
 - Radial electron drift → azimuthal electric field
 - No azimuthal symmetry due to Faradays law

2D Analytical Model with Infinite Electrodes

Analytical Model 2D Cross-Section

- Axial magnetic field $B_z = B_0 \cdot \vec{z}$
- Circular hollow electron beam @ $r < R$
- Outer boundary with infinite electrodes @ $r = R$
- Electric potential at the angular position θ of the boundary is defined to
 - $\varphi(\theta, t) = \varphi_0 \cdot \sin\left(n \cdot \theta + 2\pi \cdot \frac{t}{T}\right)$
 - With amplitude φ_0 , azimuthal periodic factor n , time t and period length T



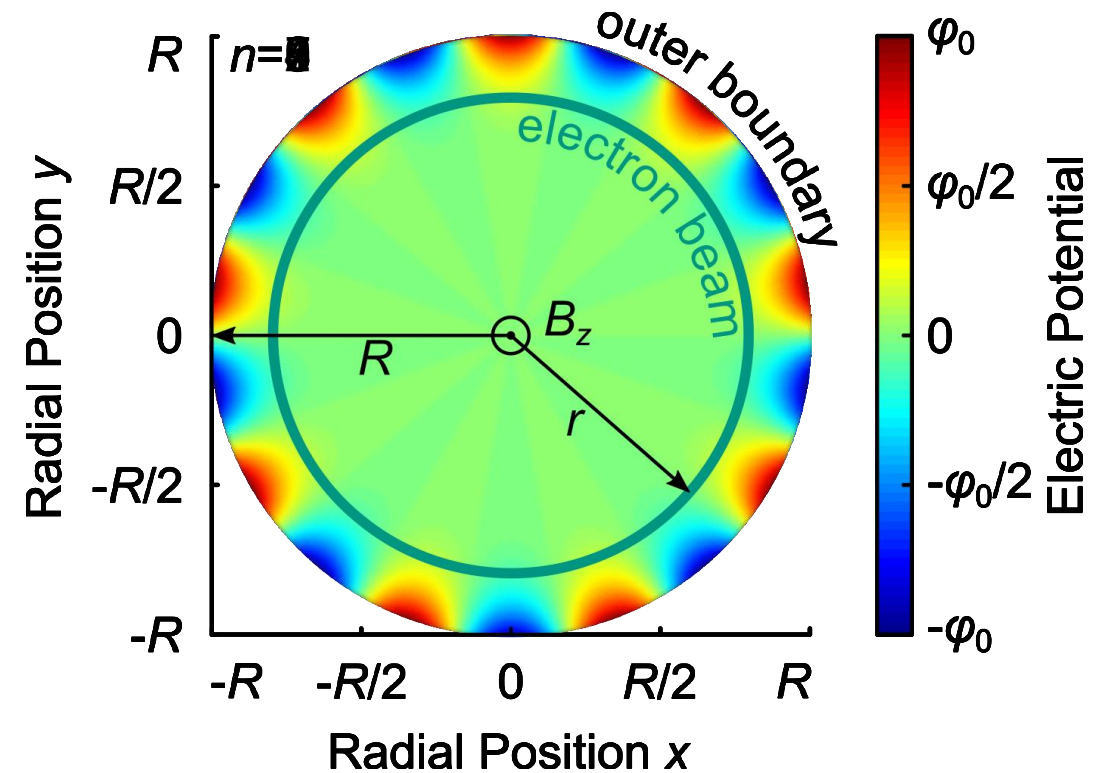
Analytical Model 2D Cross-Section

- Electric potential in the cross-section is calculated by Laplace equation to

$$\varphi(r, \theta, t) = \frac{r^n}{R^n} \cdot \varphi_0 \cdot \sin\left(n \cdot \theta + 2\pi \cdot \frac{t}{T}\right)$$

- The electric field is $\vec{E} = -\vec{\nabla}\varphi$
- The drift velocity is $\vec{v}_d = \vec{E} \times \vec{B} / |\vec{B}|^2$

$$\vec{v}_d(r, \theta, t) = -\frac{n \cdot r^{n-1}}{B_0 \cdot R^n} \cdot \varphi_0 \begin{bmatrix} \cos\left(n \cdot \theta + 2\pi \cdot \frac{t}{T}\right) \\ \sin\left(n \cdot \theta + 2\pi \cdot \frac{t}{T}\right) \end{bmatrix}^T \cdot \begin{bmatrix} \vec{r} \\ \vec{\theta} \end{bmatrix}$$



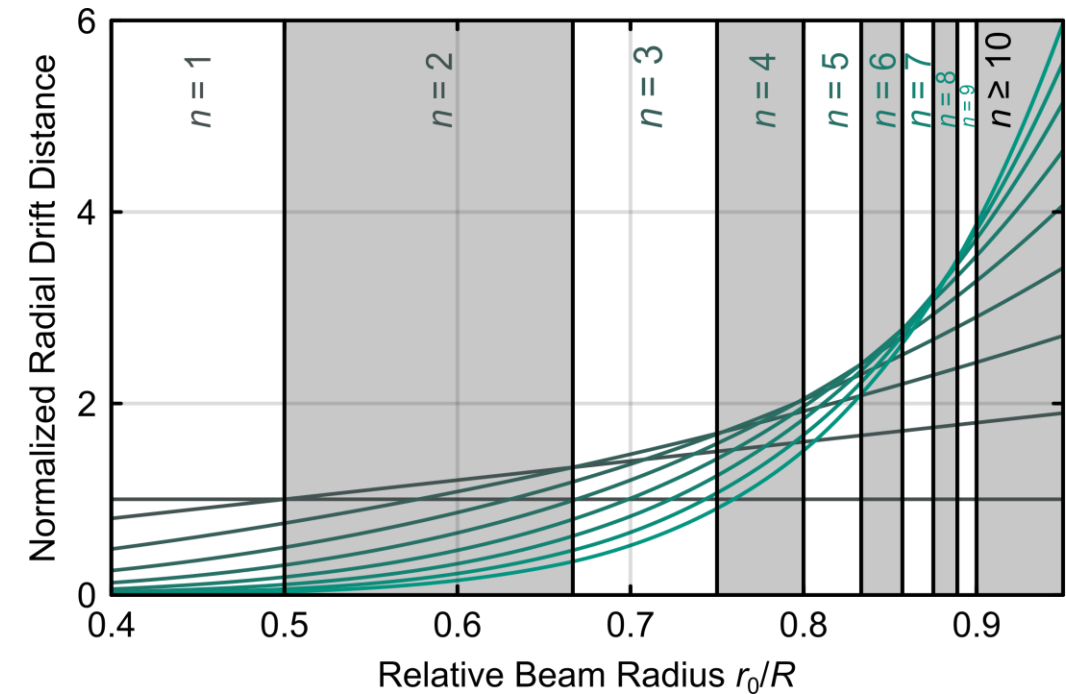
Analytical Model 2D Cross-Section

- Radial drift distance is proportional to

$$\Delta r \propto n \cdot \tau \cdot \left(\frac{r_0}{R}\right)^{n-1}$$

with the characteristic time τ

- Optimal azimuthal periodic factor n for a given relative beam radius
- Maximum relative beam radius $r_0/R := 0.85$
➡ $n \leq 6$



2D Analytical Model with Discrete Electrodes

Analytical Model – Limited Number of Potentials

- Number of electrodes is limited in a realistic system
- Discrete electrodes at angular position

$$\theta(i) = \frac{2\pi}{n} \cdot \left(\frac{i}{p} - \frac{1}{4} \right)$$

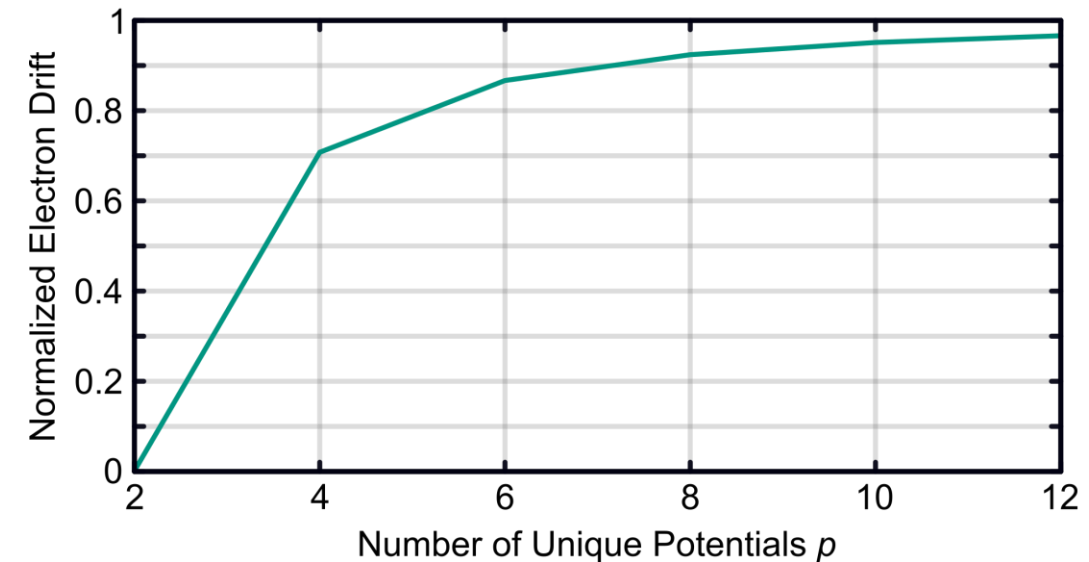
with the number of unique potentials p for $i = 1$ to $p \cdot n$

- The electric potential between the electrodes i and j

$$|\varphi(i, j, t)| \leq \left| \frac{\varphi(\theta(i), t) + \varphi(\theta(j), t)}{2} \right|$$

$$= \varphi_0 \cdot \cos\left(\frac{\pi}{p}\right) \cdot \left| \sin\left(\pi \cdot \left(\frac{i+j}{p} - \frac{1}{2}\right) + 2\pi \cdot \frac{t}{T}\right) \right|$$

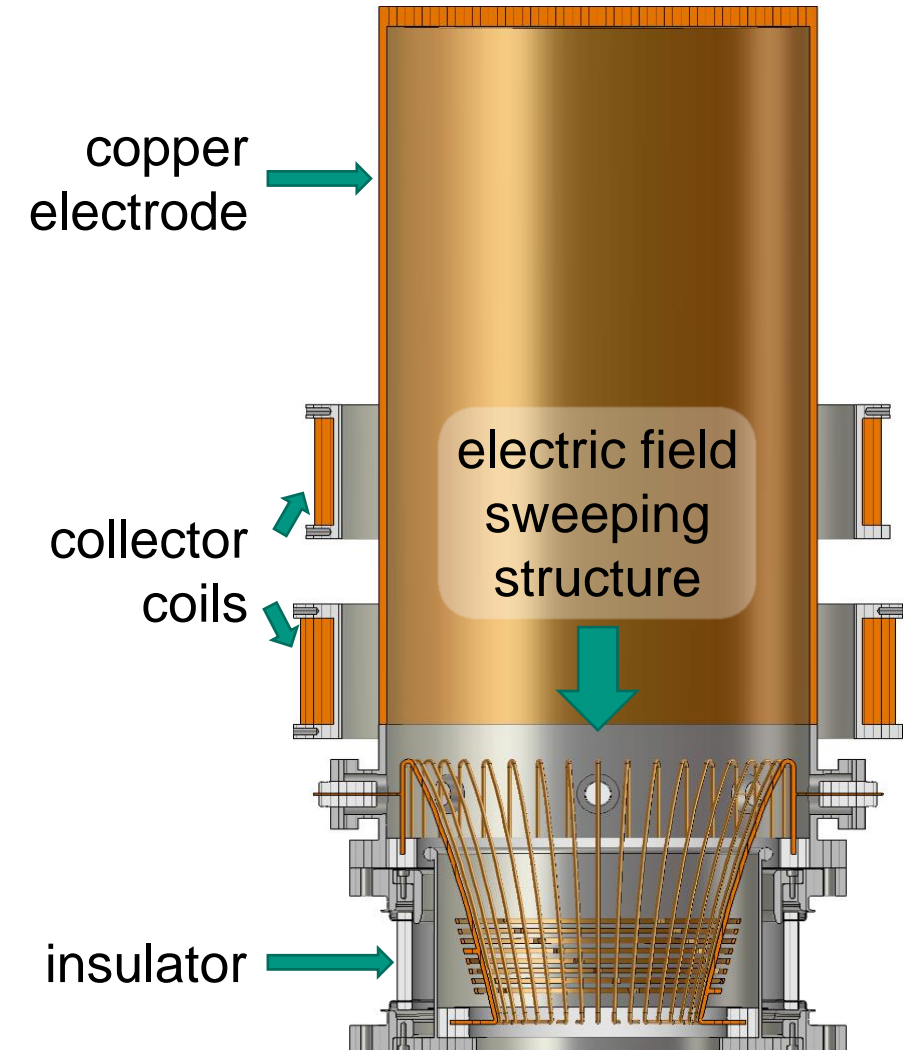
- Maximum potential between two electrodes is limited



3D Conceptual Design

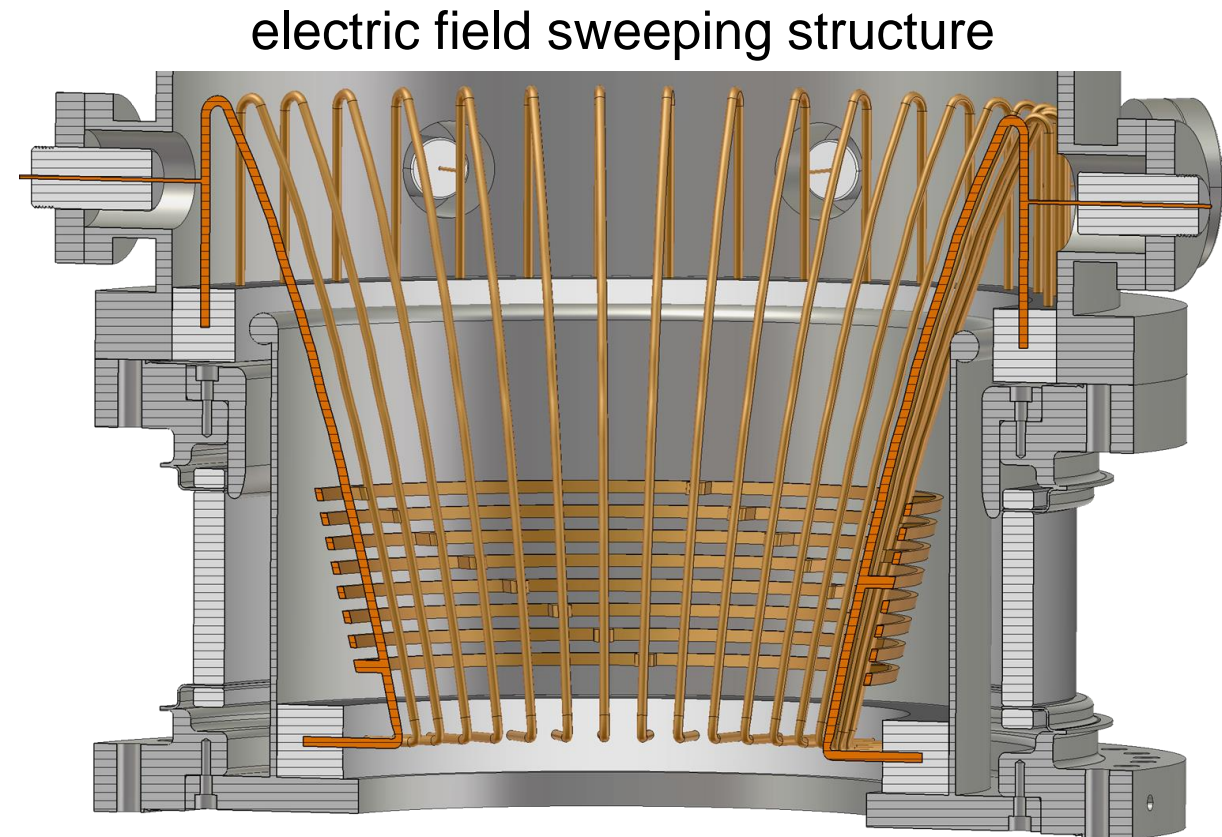
Overview of Conceptual Design

- Electric field sweeping structure at collector entrance
 - Large radius for reduced electric field
 - Low magnetic field (40 – 120 mT)
 - Space to place electrodes
- Large ceramic for depression potential
- Two DC collector coils
- Inner collector radius: 200 mm
- Length of copper section: 700 mm



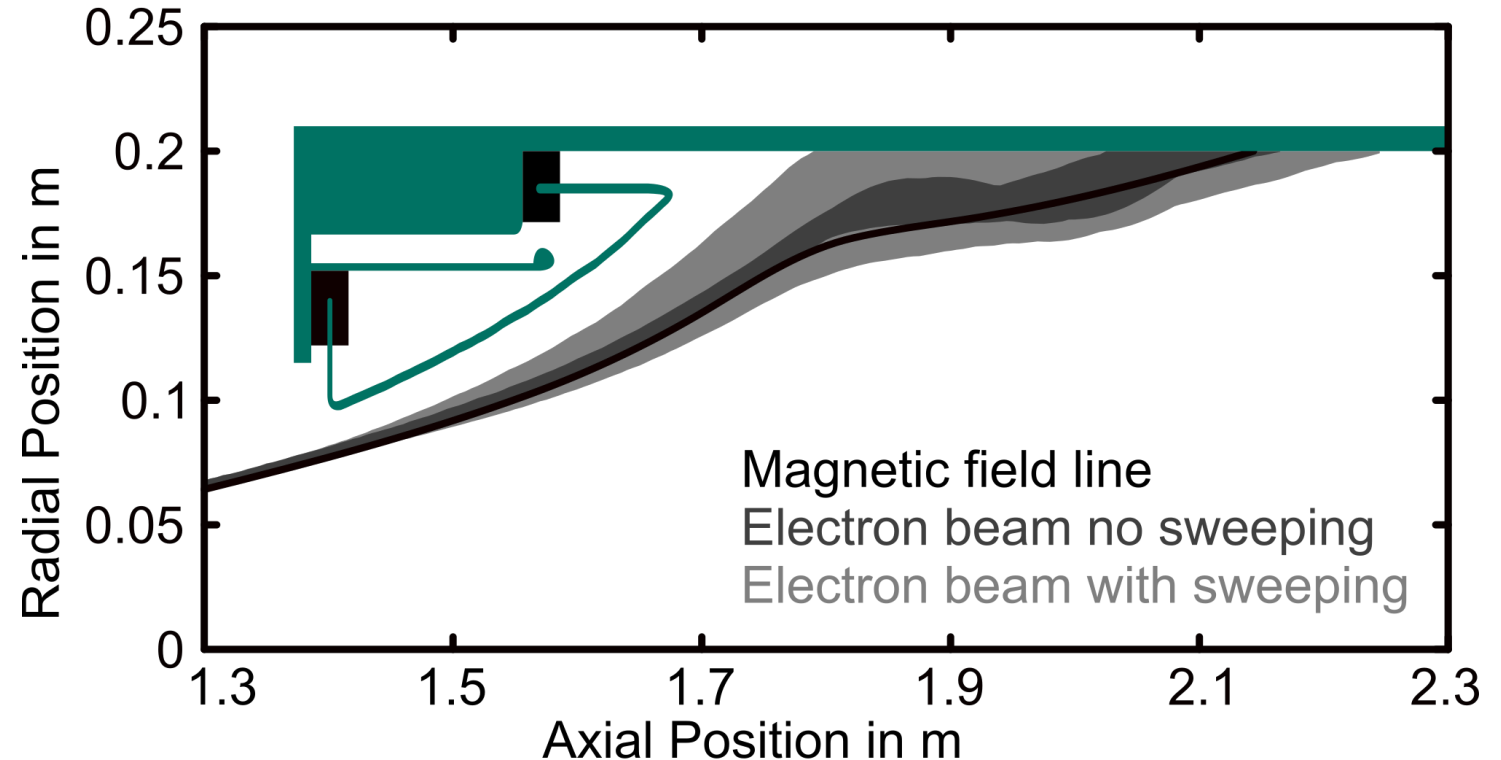
Detailed Overview of Conceptual Design

- Azimuthal periodic factor $n = 5$
 - Optimal for $r_0/R = 0.8 - 0.8\bar{3}$
 - Maximum $r_0/R := 0.85$
 - Minimum $r_0/R \approx 0.67 - 0.81$
- Unique potentials $p = 8$
 - 45° phase difference
 - 8 high voltage feedthroughs
 - Oscillating between body and depression potential → maximum potential difference
- 40 electrodes in 9° angle steps
- Internal potential distribution
- Two internal ceramic rings for mechanical support



Magnetic Field of Conceptual Design

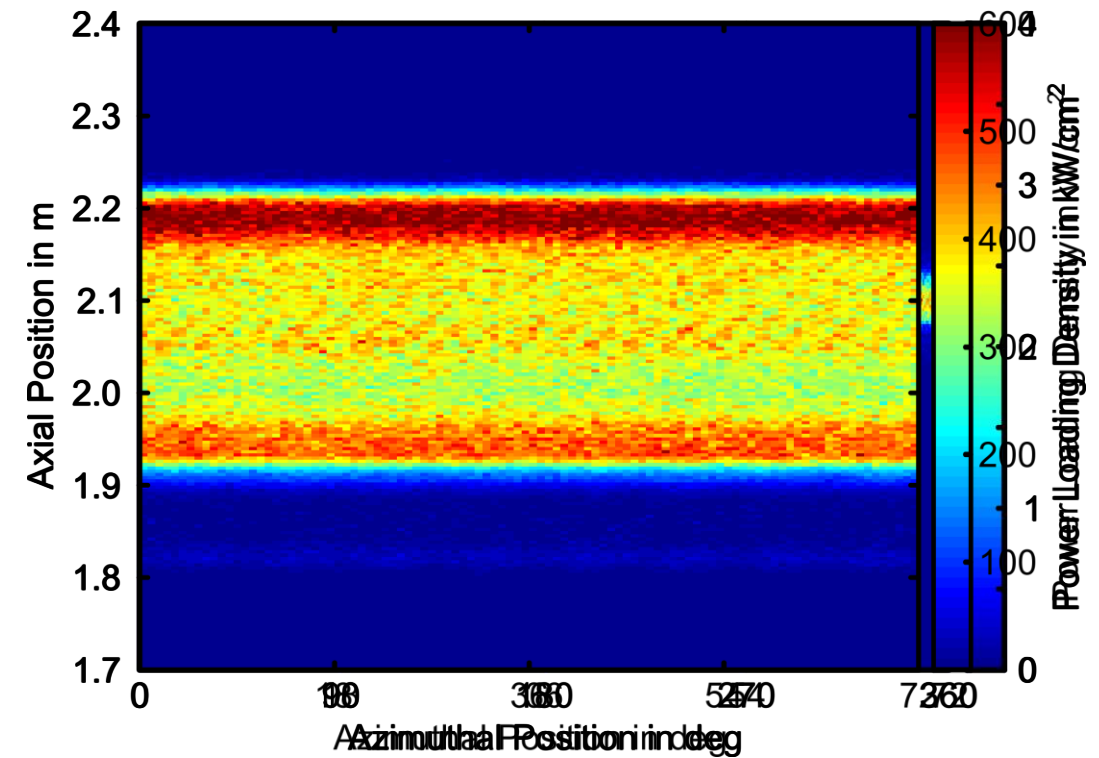
- Constant magnetic field is adjusted
 - Shallower incident angle at wall
 - Non adiabatic transition for increased beam thickness
- ➡ Modification is required



Simulation Results

Wall Loading of Conceptual Design

- Instantaneous wall loading
 - Traditional collector of same size: $\sim 6 \text{ kW/cm}^2$
 - Here without sweeping potential: $\sim 3 \text{ kW/cm}^2$
- Electric field sweeping is applied
 - Axial position of the beam on the wall is varied
 - 72° symmetry ($n = 5$)
 - Instantaneous wall loading: $\sim 4 \text{ kW/cm}^2$
- Time average
 - Homogeneous power loading distribution
 - Maximum average wall loading: $\sim 600 \text{ W/cm}^2$



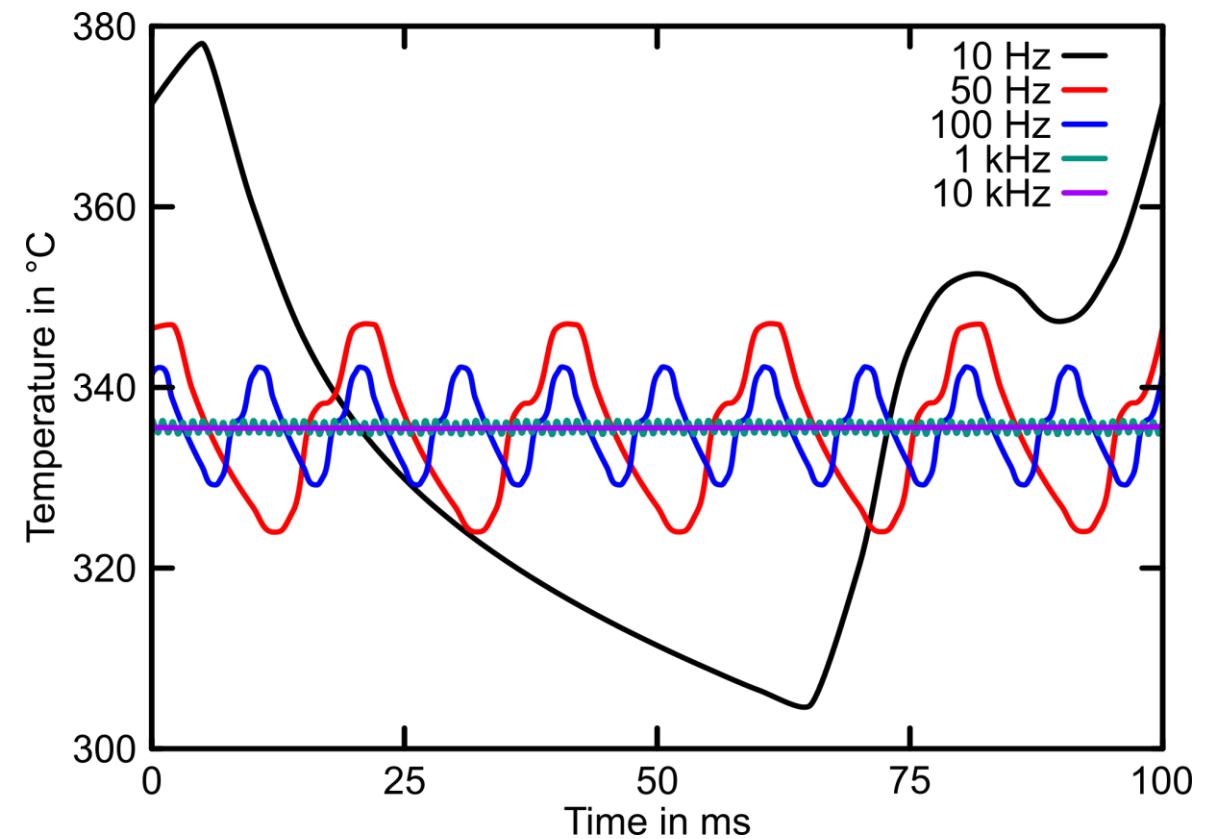
Influence of Sweeping Frequency

- Temperature variation ΔT is reduced with increasing sweeping frequency

Frequency	ΔT
10 Hz	73.5 K
50 Hz	23.0 K
100 Hz	12.9 K
1 kHz	1.6 K
10 kHz	0.2 K

- Average temperature not influenced
- ➡ Less cyclic fatigue

Temperature over time at a sample point



Conclusion

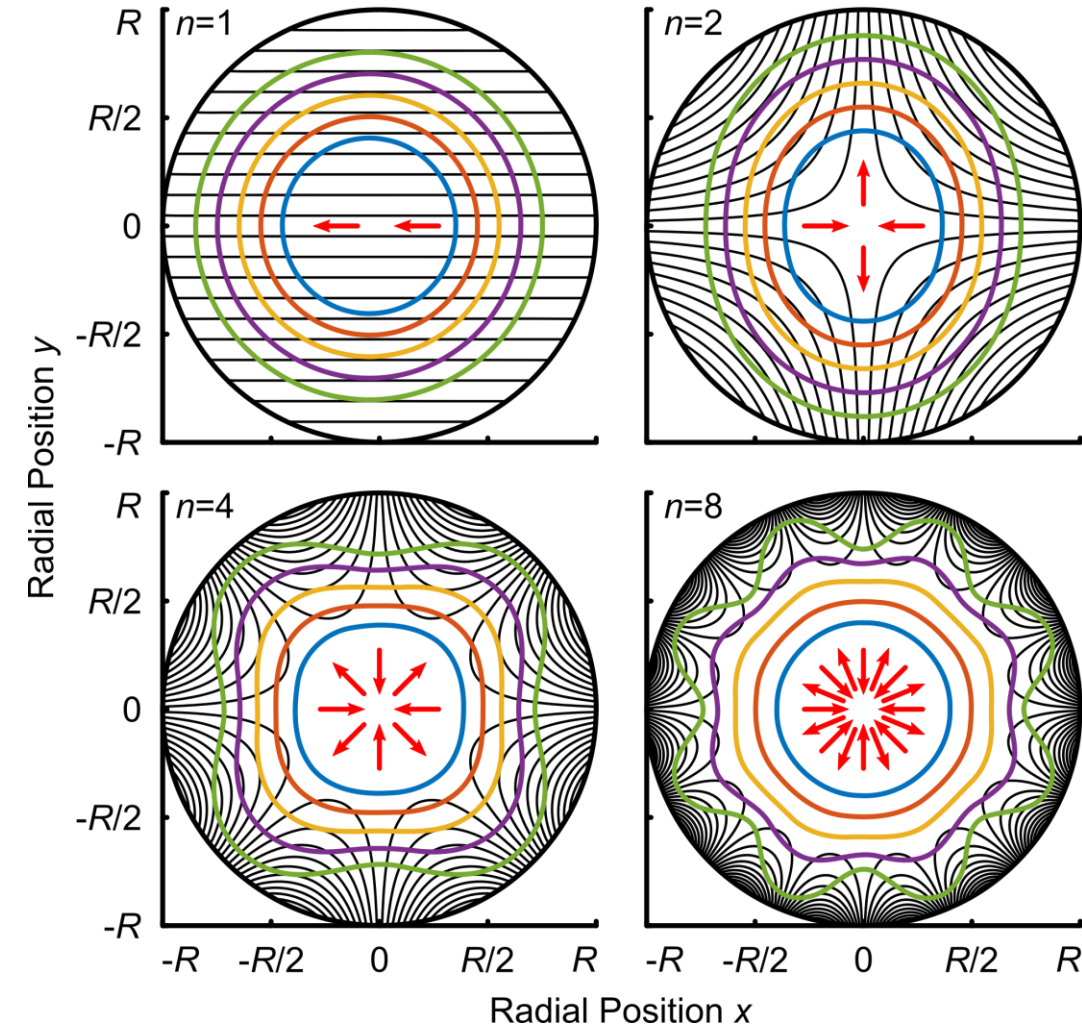
- An electric field sweeping system for a high power gyrotron was designed and analytically optimized
- Achieved strong $E \times B$ drift in radial direction
- Optimized static magnetic field for amplified effect in axial direction
- Temperature variation is significantly reduced with increasing sweeping frequency

Analytical Model 2D Cross-Section

- Radial drift distance is proportional to

$$\Delta r \propto n \cdot \tau \cdot \left(\frac{r_0}{R}\right)^{n-1}$$

with the characteristic time τ



Cutoff Frequency of Sweeping System

■ Cutoff frequency for TE mode

$$f_{c_{nm}} = \frac{k_c}{2\pi\sqrt{\mu\epsilon}} = \frac{p'_{nm}}{2\pi a\sqrt{\mu\epsilon}}$$

■ Radius a = 200 mm

- $f_{c1,1} = 439$ MHz
- $f_{c2,1} = 729$ MHz
- $f_{c3,1} = 1.00$ GHz
- $f_{c4,1} = 1.27$ GHz
- $f_{c5,1} = 1.53$ GHz
- $f_{c6,1} = 1.79$ GHz

n	m = 1
1	1.8412
2	3.0542
3	4.2012
4	5.3175
5	6.4156
6	7.5013
7	8.5778
8	9.6474

